

Given $\dot{x} = f(x)$; $x(0) = x_0$. Find the solution $x(t)$.

① Analytically: (rare)

example: $\dot{x} = ax$; $x(0) = x_0$ $a, x_0 \in \mathbb{R}$

technique: separation of variables

$$\frac{dx}{dt} = ax \Rightarrow \int \frac{dx}{x} = \int a dt + c$$

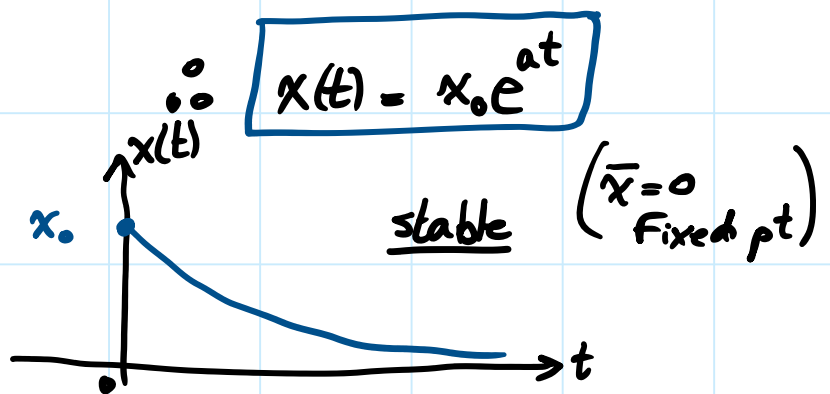
$$\Rightarrow e^{\ln|x|} = e^{(at + c)}$$

$$\Rightarrow \cancel{x(t)} = e^{at} \textcircled{c} \rightarrow k \Rightarrow x(t) = k e^{at}$$

$$x(0) = \boxed{k = x_0}$$

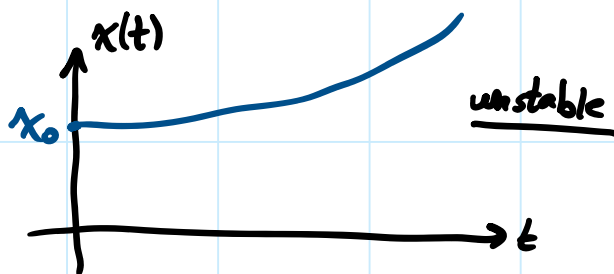
if $a < 0$

$$\lim_{t \rightarrow \infty} x(t) = \lim_{t \rightarrow \infty} x_0 e^{at} = 0$$



if $a > 0$

$$\lim_{t \rightarrow \infty} x(t) = \infty$$



special case: if $x_0 = 0$

$$x(t) = x_0 e^{at} = 0$$

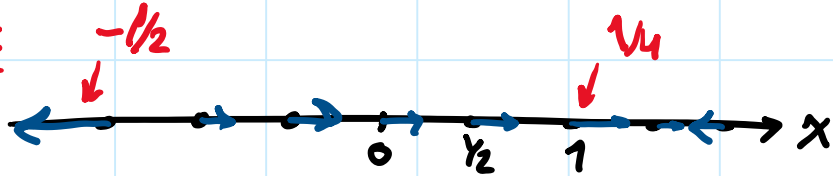
Fixed point but unstable!

② Numerically: If the D.E. is not analytically solvable

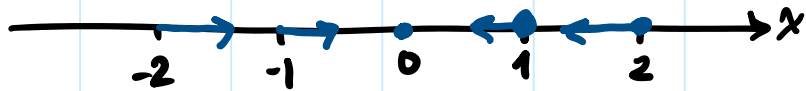
Euler's Method (the intuitive approach)

Vector Field: It is a field of vectors that completely defines a function.

example in 1D: $-1/2$



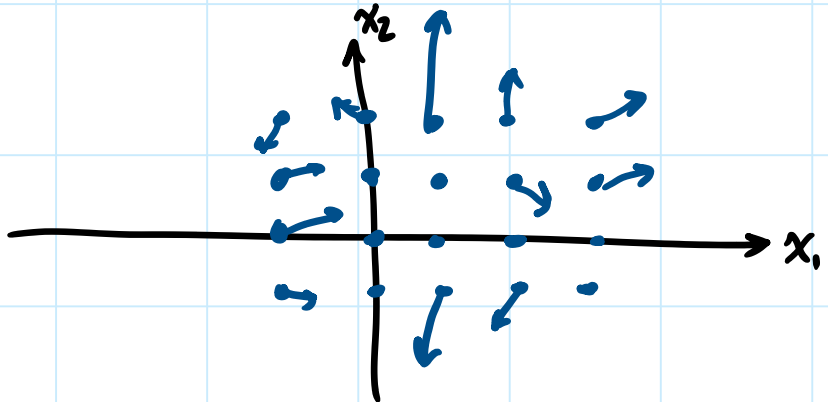
$$f: \mathbb{R} \rightarrow \mathbb{R} : f(x) = -2x$$



example in 2D:

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f(x_1, x_2) = \begin{bmatrix} x_1^2 + x_2^2 \\ x_2 \end{bmatrix}$$

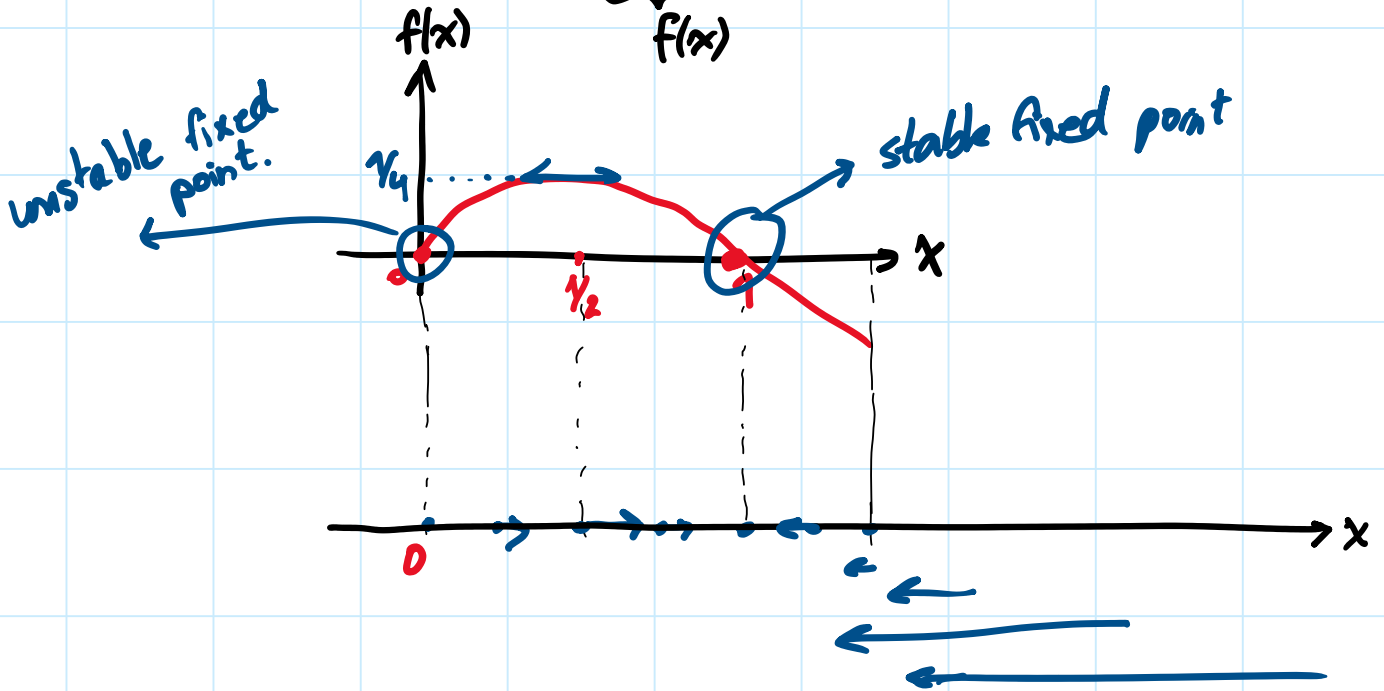


Question: How is all of this related to solving D.E.?

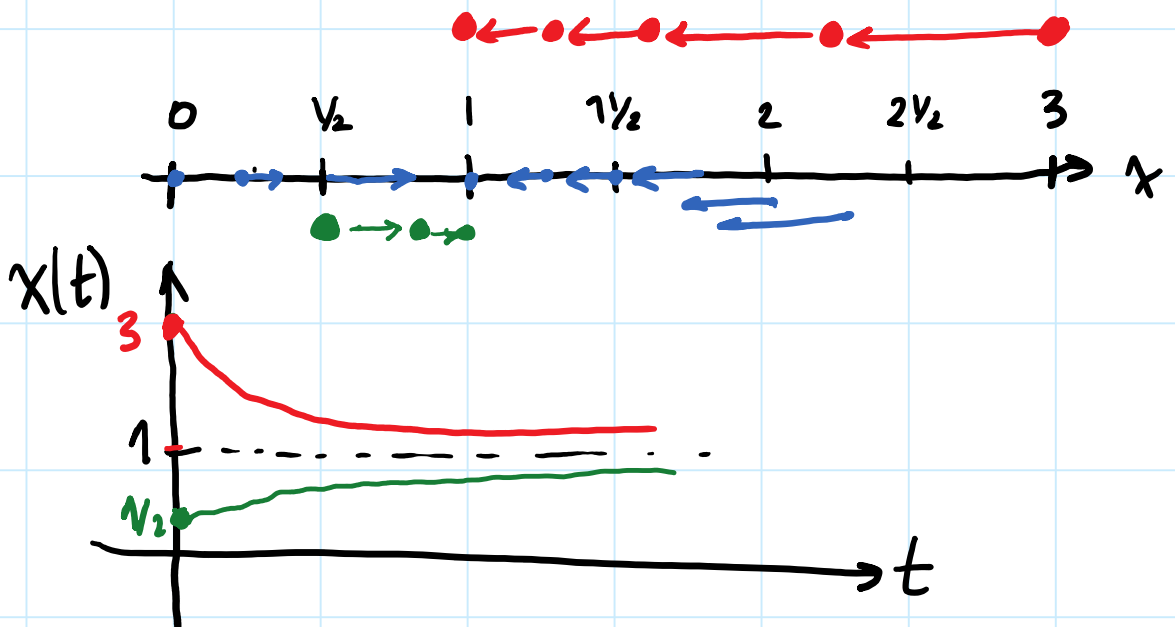
Example modeling population growth

$$\dot{x} = x \quad \frac{\dot{x}}{x} = 1 - x \quad x \geq 0 \quad x \in \mathbb{R}^+$$

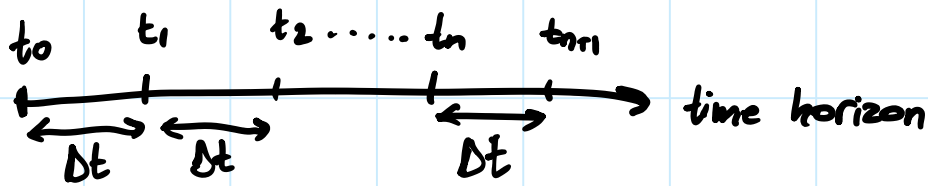
$$\Rightarrow \dot{x} = \underbrace{x(1-x)}_{f(x)} \dots \text{Logistic Model}$$



solve graphically $\dot{x} = x(1-x)$
 $x(0) = 1/2$



Goal: Build a mathematical framework for the intuition.



$x_n \approx x(t_n)$ $x(t_n)$: exact solution, x_n : approx.

Algorithm: Given x_n ; how to find x_{n+1} ?

$$x_{n+1} = x_n + \text{push of vector (@ } x_n) \\ \parallel \\ \Delta t \cdot f(x_n)$$

∴ Euler's Method: $x_{n+1} = x_n + \Delta t f(x_n)$

Step by step:

$$\dot{x} = f(x), \quad x(0) = x_0$$

$$(1) \quad x_1 = x_0 + \Delta t f(x_0)$$

$$(2) \quad x_2 = x_1 + \Delta t f(x_1)$$

⋮

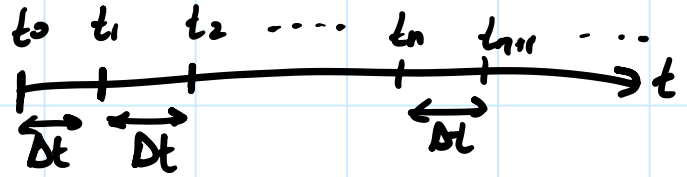
$$(n) \quad x_n = x_{n-1} + \Delta t f(x_{n-1})$$

$$(n+1) \quad x_{n+1} = x_n + \Delta t f(x_n)$$

⋮

Euler's Method (the mathematical approach)

$$\dot{x} = f(x) ; x(0) = x_0$$



$$t_n = t_0 + n \Delta t$$

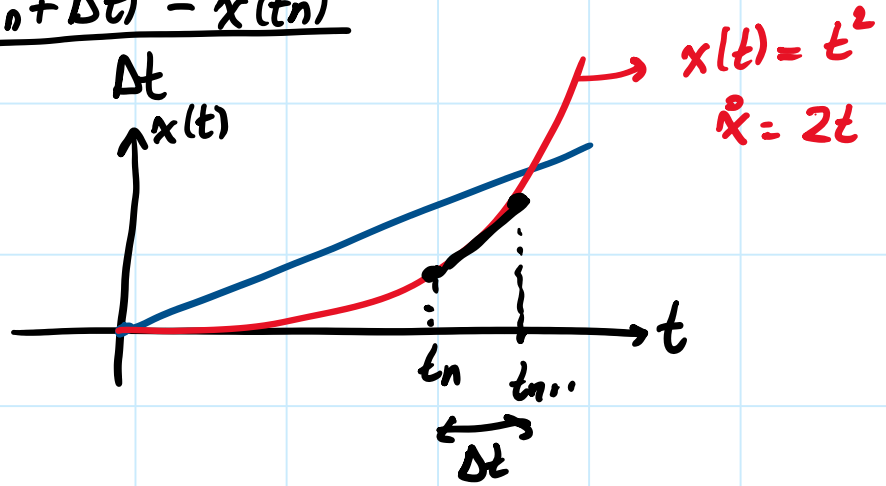


key ingredient for Euler's Method

$$\dot{x}(t_n) = \lim_{\Delta t \rightarrow 0} \frac{x(t_n + \Delta t) - x(t_n)}{\Delta t}$$

$$x(t) = t$$

$$\dot{x}(t) = 1$$



$$\dot{x}(t) = f(x)$$

@ t_n

$$\frac{x(t_n + \Delta t) - x(t_n)}{\Delta t} = f(x(t_n))$$

$$\frac{x_{n+1} - x_n}{\Delta t} = f(x_n) \rightarrow$$

$$x_{n+1} = x_n + \Delta t f(x_n)$$

push

Modified Euler Method:

$$\begin{array}{l} \text{trial step} \\ \text{real step:} \end{array} \left\{ \begin{array}{l} \tilde{x}_{n+1} = x_n + \Delta t f(x_n) \\ x_{n+1} = x_n + \frac{1}{2} [f(x_n) + f(\tilde{x}_{n+1})] \Delta t \end{array} \right.$$

Runge-Kutta Method:

$$x_{n+1} = x_n + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)$$

where

$$\left\{ \begin{array}{l} k_1 = f(x_n) \Delta t \\ k_2 = f(x_n + \frac{1}{2} k_1) \Delta t \\ k_3 = f(x_n + \frac{1}{2} k_2) \Delta t \\ k_4 = f(x_n + k_3) \Delta t \end{array} \right.$$

Error of approximation

$$E_n := |x(t_n) - x_n|$$

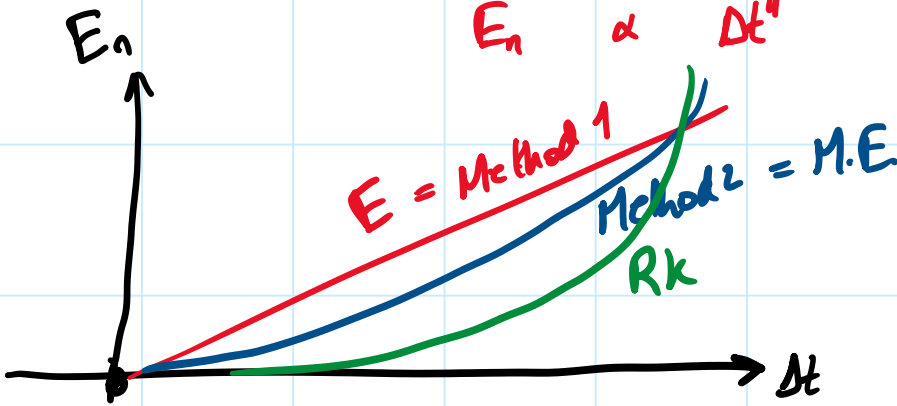
↑ exact solution
← approximated solution for the numerical method

$$E_n \propto \Delta t$$

$$E_n \propto \Delta t^2$$

$$E_n \propto \Delta t^4$$

Euler's method
 Modified Euler
 Runge-Kutta (4th order)



$$E_n \xrightarrow{\Delta t \rightarrow 0} 0$$